

# ECSE 6520: Estimation and Detection Theory

## Sufficient Statistic

Class Notes - 4

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# 1 Sufficient Statistics

Many detection/estimation/classification problems have the following common structure. A continuous time waveform  $\{x(t)|t \in \mathbb{R}\}$  is measured at  $n$  time instants  $t_1, \dots, t_n$  producing the vector  $x = [x_1, \dots, x_n]^T$  where  $x_i = x(t_i)$ . The vector  $x$  is modelled as a realization of a random vector  $X$  with a joint distribution which is of known form but depends on a handful ( $p$ ) of unknown parameters  $\theta = [\theta_1, \dots, \theta_p]^T$ .

- $X = [X_1, \dots, X_n]^T$ ,  $X_i = X(t_i)$ , is a vector of random measurements or observations taken over the course of the experiment
- $\mathcal{X}$  is sample or measurement space of realizations  $x$  of  $X$ .
- $\mathcal{B}$  is the event space induced by  $X$ , e.g., the Borel subsets of  $\mathbb{R}^n$ .
- $\theta \in \Theta$  is an unknown parameter vector of interest.
- $\Theta$  is parameter space for the experiment.
- $P_\theta$  is a probability measure on  $\mathcal{B}$  for given  $\theta$ .  $\{P_\theta\}_{\theta \in \Theta}$  is called the statistical model for the experiment. Note that the probability model induces the joint cumulative distribution function of  $X$ .
- Our objective is to infer properties of  $\theta$  knowing only the parametric form of the statistical model, i.e, the pdf  $f_\theta(x)$  of  $X$ , given a realization  $x$  of  $X$ . In other words, we want to come up with a function, called inference function, which maps  $X$  to a subset of the parameter space, say for the purpose of designing an estimator, classifier or a detector.
- Is it possible to compress the measurement  $x$  into a low dimensional statistic without effecting the quality of the inference about  $\theta$ ?

- In other words, does there exist  $T = \tau(X)$ , where the dimension of  $T$  is  $M < N$ , such that  $T$  carries all the useful information on  $\theta$ ?
- If so, for the purpose of studying  $\theta$ , we could discard the raw measurements  $x$  and retain only the compressed statistics  $t$ .

**Definition 1 *Sufficient Statistics*** - Let  $f_\theta(x)$  be the pdf of the random variable  $X$ . The statistic  $T = \tau(X)$  is a sufficient statistics for  $\theta$  if the conditional distribution of  $X$  given  $T$  is independent of  $\theta$ . Equivalently, the functional form of  $f_{X|T}(x|t)$  does not involve  $\theta$ .

## 1.1 The Fisher-Neyman Factorization Theorem

In general, it is difficult to verify the definition of sufficient statistic directly since it involves derivation of the conditional probability. The Fisher-Neyman Factorization theorem allows us to verify sufficient statistics more readily.

**Theorem 1 *The Fisher-Neyman Factorization Theorem*** - Let  $f_\theta(x)$  be the pdf or the pmf of the random variable  $X$ . The statistic  $T = \tau(X)$  is a sufficient statistics for  $\theta$  iff there exists functions  $b_\theta(t)$  and  $a(x)$  such that

$$f_\theta(x) = b_\theta(\tau(x))a(x).$$

- The theorem gives us a formula for  $f_{X|T}(x|t)$ , namely

$$f_{X|T}(x|t) = \frac{a(x)}{\sum_{\{x'|\tau(x')=t\}} a(x')}.$$

- The theorem states that  $\tau(X)$  is sufficient for  $\theta$  if and only if the pdf or pmf of  $X$  may be written as a scale constant, dependent on  $x$  and  $t$ , but independent on  $\theta$ , times the pdf or pmf of  $T$ .
- The theorem also shows that the scale constant is the conditional density of  $x$ , given  $t$ , and it shows how to compute the pdf or pmf for the sufficient statistics  $T$ .

- If an invertible function is applied to a sufficient statistics, the result is again a sufficient statistic.

## 1.2 Rao-Blackwell Theorem

The importance of the sufficient statistics is reflected in the following theorem.

**Theorem 2 Rao-Blackwell Theorem** - Let  $f_\theta(x)$  be the pdf or the pmf of the random variable  $X$ . Let  $T = \tau(X)$  be a sufficient statistic for  $\theta$ . Let  $\hat{\theta}_1(x)$  be an estimator of  $\theta$  and define the mean square error

$$MSE(\hat{\theta}_1) = E[|\hat{\theta}_1(x) - \theta|^2].$$

Define

$$\hat{\theta}_2(x) = E[\hat{\theta}_1(x)|T = \tau(x)].$$

Then

$$MSE(\hat{\theta}_2) \leq MSE(\hat{\theta}_1)$$

with equality if and only if  $\hat{\theta}_1 = \hat{\theta}_2$  with probability 1.

**Remarks -**

- Given any estimate  $\hat{\theta}_1$  that is NOT a function of a sufficient statistic, there exist a better estimate with respect to MSE.
- We may restrict our search for estimators to functions of sufficient statistic.

## 2 Minimal Sufficient Statistics

- What is the maximum possible amount of reduction one can apply to the data sample without losing information concerning how the model depends on  $\theta$ ? The answer to this question lies in the notion of a *minimal sufficient statistic*.

- Minimal sufficient statistic cannot be reduced any further without loss in information. In other words, any other sufficient statistic can be reduced down to a minimal sufficient statistic without information loss. Since reduction of a statistic is accomplished by applying a functional transformation we have the following definition:

**Definition 2 *Minimal Sufficient Statistics*** -:  $T_{min}$  is a minimal sufficient statistic if it can be obtained from any other sufficient statistic  $T$  by applying a functional transformation to  $T$ . Equivalently, if  $T$  is any sufficient statistic there exists a function  $q$  such that  $T_{min} = q(T)$ .

Minimal sufficient statistics are not unique: if  $T_{min}$  is minimal sufficient  $h(T_{min})$  is also minimal sufficient if  $h$  is any invertible function. Minimal sufficient statistics can be found in a variety of ways. One way is to find a *complete sufficient statistic*.

### 3 Complete Sufficient Statistic

**Definition 3 *Complete Sufficient Statistic*** - A sufficient statistic  $T$  is complete if

$$E_{\theta}[g(T)] = 0, \quad \text{for all } \theta \in \Theta$$

implies that the function  $g$  is identically zero, i.e.,  $g(t) = 0$  for all values of  $t$ .

**Theorem 3** Under general conditions, if  $T$  is a complete sufficient statistic, then  $T$  is minimal.

### 4 The Exponential Family

In general, sufficient statistics, especially ones that are minimal and complete, can be difficult to find. For a special family of distributions, however, we can immediately identify a complete minimal sufficient statistic.

**Definition 4** *The Exponential Family* - The distribution of the random variable  $X$  is said to belong to the exponential family of distributions if its pmf/pdf can be expressed as

$$f_{\theta}(x) = a(\theta)b(x) \exp\{c(\theta)^T \tau(x)\}$$

for some  $a$ ,  $b$ ,  $c$ , and  $\tau$ , where the dimension  $p$  of  $\theta$  is also the dimension of  $c(\theta)$  and  $\tau(x)$ .

- Many common distributions belong to the exponential family, including Gaussian with unknown mean and/or variance, Poisson, exponential, gamma, binomial, and multinomial.

**Theorem 4** *If the distribution of  $X$  belongs to the exponential family, then  $T = \tau(X)$  is a sufficient statistic.*

Note the  $\tau(x)$  in the above theorem is the  $\tau(x)$  in the definition of the exponential family.

**Theorem 5** *Under certain “reasonable” conditions,  $T = \tau(x)$  is a complete and minimal sufficient statistic for  $\theta$ .*