ECSE 6520: Estimation and Detection Theory

Cramer-Rao Lower Bound

Class Notes - 8

February 17th, 2014

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1 Importance of Cramer-Rao Lower Bound

- CRLB is the minimum achievable variance for an unbiased estimator. Hence, if an unbiased estimator achieves CRLB, it is MVUE. (But, the opposite is not necessarily true.)
- CRLB provides a benchmark against which we can check the performance of any estimator.
- The CRLB can be defined for both random and non-random parameters. However the CRLB is more useful for non-random parameters as it can be used to establish optimality or near optimality of an unbiased candidate estimator.
- The theory behind CRLB tells us exactly when CRLB is achievable.

2 Fisher Information Matrix and Cramer-Rao Lower Bound

For the rest of this topic, we will make the following assumptions:

- Θ is an open subset in \mathbb{R}^p .
- $f_{\theta}(x)$ is smooth and differentiable in θ .

Definition 1 Score Function - Let $f_{\theta}(x)$ be the pdf of X and let $f_{\theta}(x)$ be smooth and differentiable in θ . We call

$$s(\theta, x) = \frac{\partial}{\partial \theta} \ln f_{\theta}(x)$$

the score function.

Note that $\ln f_{\theta}(x)$ is referred to as the log-likelihood function.

Definition 2 Fisher Information Matrix - Let $f_{\theta}(x)$ be the pdf of X and let $f_{\theta}(x)$ be smooth and differentiable in θ . We call

$$F(\theta) := E[(\frac{\partial}{\partial \theta} \ln f_{\theta}(x))(\frac{\partial}{\partial \theta} \ln f_{\theta}(x))^{T}]$$

the Fisher information matrix.

Theorem 1 Cramer-Rao Lower Bound - Let $X \in \mathcal{X} \subseteq \mathbb{R}^N$, $\theta \in \Theta$ and let Θ be an open subset of \mathbb{R}^p . Let the pdf of X, f_{θ} , be a smooth differentiable function of θ and $\hat{\theta}$ be an unbiased estimate of θ . Assume that the covariance of $\hat{\theta}$ and the Fisher information matrix $F(\theta)$ are non-singular. Then

$$Cov(\hat{\theta}) = E[(\hat{\theta} - \theta)(\hat{\theta} - \theta)^T] \ge F^{-1}(\theta).$$

Furthermore, an unbiased estimate is efficient, that is,

 $E[\hat{\theta}] = \theta$

$$Cov(\hat{\theta}) = E[(\hat{\theta} - \theta)(\hat{\theta} - \theta)^T] = F^{-1}(\theta)$$

if and only if

$$F(\theta)(\hat{\theta} - \theta) = s(\theta, x).$$

The CRLB for the scalar parameter can be stated as follows:

Theorem 2 CRLB for the scalar case - Let the pdf of X, $f_{\theta}(x)$ be a smooth differentiable function of θ . If $\hat{\theta}$ is an unbiased estimate of θ , then

$$Var(\hat{\theta}) \ge \frac{1}{F(\theta)}$$

where $F(\theta) = E[(\frac{\partial}{\partial \theta} \ln f_{\theta}(x))^2]$ is the Fisher information.

Some Facts relevant to the proof of CRLB theorem

- Note that $X \in \mathcal{X}$ can be discrete or continuous.
- $Cov(\hat{\theta}) \ge F^{-1}(\theta)$ means $Cov(\hat{\theta}) F^{-1}(\theta)$ is non-negative definite.
- The score function $s(\theta, x)$ has zero mean, i.e.,

$$E[\frac{\partial}{\partial \theta} \ln f_{\theta}(x)] = 0.$$

(This is true only if a certain integration and differentiation operators can be interchanged. For most pdf's this is true.)

• The covariance of the score function

$$\mathbf{F}(\theta) := E[s(\theta, x)s(\theta, x)^T] = E[(\frac{\partial}{\partial \theta} \ln f_{\theta}(x))(\frac{\partial}{\partial \theta} \ln f_{\theta}(x))^T]$$

is equal to the Fisher information matrix.

• The Fisher information matrix $F(\theta)$ can be alternatively expressed as

$$\mathbf{F}(\theta) = -E\left[\frac{\partial}{\partial \theta} \left(\frac{\partial}{\partial \theta} \ln f_{\theta}(x)\right)^{T}\right].$$

• The *ij*th element of the Fisher information matrix is given by

$$F_{ij} = E[(\frac{\partial}{\partial \theta_i} \ln f_{\theta}(x))(\frac{\partial}{\partial \theta_j} \ln f_{\theta}(x))]$$
$$= E[-\frac{\partial^2}{\partial \theta_i \theta_j} \ln f_{\theta}(x)].$$

• The cross-covariance between the score function and the error between the unbiased estimate and the parameter is identity, that is

$$E[s(\theta, x)(\hat{\theta}(x) - \theta)^T] = I.$$

- An efficient estimate does not always exist.
- If an efficient estimate exists, then it is MVUE.

3 Properties of CRLB

It is insightful to study the properties of the CRLB in the scalar case.

- **Property 1**: The Fisher information is a measure of the average curvature profile of the log likelihood function $\ln f_{\theta}(x)$ near θ .
- **Property 2**: Let $F_N(\theta)$ be the Fisher information matrix for a sample of N i.i.d. random variables $X_1, X_2, ..., X_N$. Then,

$$F_N(\theta) = NF_1(\theta).$$

As a result, $Var[\theta_i] = \mathcal{O}(1/N)$ is expected for "good" estimators.

• **Property 3**: Asymptotic Efficiency - If an estimator is asymptotically unbiased and its covariance decays with optimal rate

$$\lim_{N \to \infty} NCov(\hat{\theta}) = [\mathbf{F}_1(\theta)]^{-1},$$

then, $\hat{\theta}$ is said to be asymptotically efficient.

In particular, if $f_{\theta}(x) = a(\theta)b(x) \exp\{c^{T}(\theta)\tau(x)\}$ and $E[\tau(x)] = \theta$, then

$$\hat{\theta} = \frac{1}{N} \sum_{i=1}^{N} \tau(x_i)$$

is an unbiased and efficient estimator of θ .

• **Property 4**: Under the assumptions of the CRLB,

$$\sum_{ij} Cov(\hat{\theta}) \geq \sum_{ij} [\mathbf{F}^{-1}(\theta)]_{ij}$$

and

$$Var(\hat{\theta}_i) \ge \mathbf{F}^{-1}(\theta)_{ii}.$$

The vector CRLB implies scalar lower bounds on each component of $\hat{\theta}$.

• **Property 5**: If an estimator $\hat{\theta}$ satisfies

$$\nabla_{\theta} \ln f_{\theta}(x) = K_{\theta}(\hat{\theta} - \theta),$$

then we can immediately conclude the followings:

- 1. $\hat{\theta}$ is unbiased.
- 2. $\hat{\theta}$ is efficient and thus its components are UMVE.
- 3. The covariance of $\hat{\theta}$ is given by the inverse of the Fisher information matrix $F(\theta)$.
- 4. $K_{\theta} = \mathbf{F}(\theta)$ and $Cov(\hat{\theta}) = K_{\theta}^{-1}$.