

## The relation between uniform stability and comparison functions

Consider the system :  $\dot{x} = f(x, t)$ ,  $f(0, t) = 0$ ,  $\forall t \geq t_0$

Lemma 4.5 :

- $0$  is uniformly stable if and only if there exist a class  $K$  function  $\alpha$  and  $c > 0$ , independent of  $t_0$ , such that :  

$$\|x(t)\| \leq \alpha(\|x(t_0)\|), \forall t \geq t_0, \forall \|x(t_0)\| < c$$
- $0$  is uniformly asymptotically stable if and only if there exist a class  $KL$  function  $\beta$  and  $c > 0$  independent of  $t_0$ , such that :  

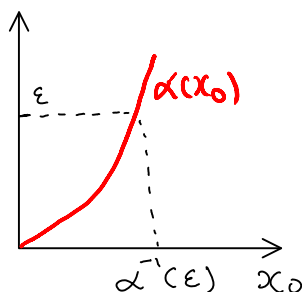
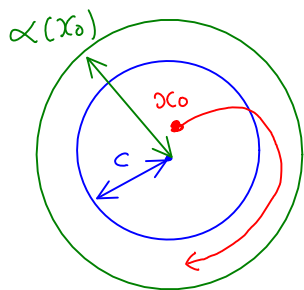
$$\|x(t)\| \leq \beta(\|x(t_0)\|, t - t_0), \forall t \geq t_0, \forall \|x(t_0)\| < c$$
- $0$  is globally uniformly asympt. stable if and only if there exists a class  $KL$  function  $\beta$  independent of  $t_0$ , such that  

$$\|x(t)\| \leq \beta(\|x(t_0)\|, t - t_0), \forall t \geq t_0$$

Proof for uniform stability :

(If) Suppose that there exist a class  $K$  function  $\alpha$  and  $c > 0$  such that  

$$\|x(t)\| \leq \alpha(\|x(t_0)\|), \forall t \geq t_0, \forall \|x(t_0)\| < c$$



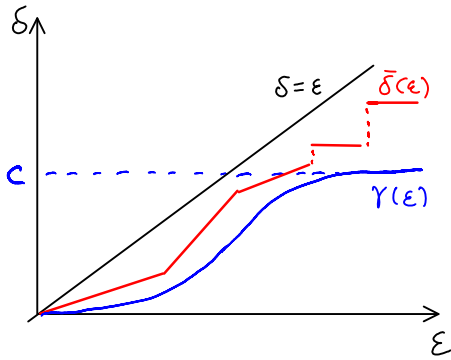
For any given  $\epsilon > 0$ ,  
 take  $\delta < \min(c, \alpha^{-1}(\epsilon))$

(Only if) Suppose that for every  $\epsilon > 0$ ,  $\exists \delta(\epsilon)$  such that  

$$\|x(t_0)\| < \delta(\epsilon) \Rightarrow \|x(t)\| < \epsilon, \forall t \geq t_0$$

$\delta(\epsilon)$  is not unique but has supremum. Define  $\bar{\delta}(\epsilon) = \sup \delta(\epsilon)$

Note that  $\bar{\delta}(\epsilon)$  is nondecreasing and positive definite,



We can always construct a class K function  $\gamma$  such that  $\gamma(\epsilon) \leq b \cdot \bar{\delta}(\epsilon)$ ,  $b < 1$

Define  $\alpha(\delta) \triangleq \gamma^{-1}(\delta) \rightarrow$  class K  
 $C \triangleq \sup_{\epsilon} \gamma(\epsilon)$

Thus  $\forall \|x(t_0)\| < C, \forall t \geq t_0,$   
 $\|x(t)\| \leq \alpha(\|x(t_0)\|)$

### Lyapunov Theory for TV systems

Thm 4.8 (modified) Let  $V(x,t): D \times [0, \infty) \rightarrow \mathbb{R}$  be a continuously differentiable function such that:

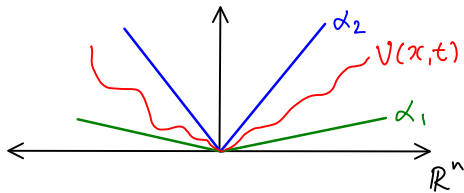
$$\alpha_1(\|x\|) \leq V(x,t) \leq \alpha_2(\|x\|)$$

$$\frac{\partial V}{\partial t} + \frac{\partial V}{\partial x} f(x,t) \leq 0$$

for all  $t \geq 0$  and  $x \in D$ , where  $\alpha_1$  and  $\alpha_2$  are class K functions

Then 0 is uniformly stable.

Proof: Notice that  $\frac{\partial V}{\partial t} \leq 0$ , thus  $V(x,t)$  is nonincreasing in  $t$ .



For any  $\epsilon > 0$ , pick  $\epsilon'$  such that

$$B(0, \epsilon') \in D$$

$$\text{Pick } \delta \leq \alpha_2^{-1}(\alpha_1(\epsilon'))$$

$$\|x(t_0)\| < \delta \Rightarrow \alpha_2(\|x(t_0)\|) < \alpha_1(\epsilon')$$

$$V(x(t_0), t_0) < \alpha_1(\epsilon')$$

$$V(x(t), t) < \alpha_1(\epsilon')$$

$$\alpha_1(\|x(t)\|) < \alpha_1(\epsilon') \Rightarrow \|x(t)\| < \epsilon'$$

Thm 4.8 is more general, since instead of  $\alpha_1$  and  $\alpha_2$ , the bounds are given by  $W_1(x)$  and  $W_2(x)$  that are continuous and +def functions in  $D$ . However, we can use the "sandwich theorem" and have  $\alpha_1(\|x\|) \leq W_1(x)$  and  $W_2(x) \leq \alpha_2(\|x\|)$ .

Thm 4.9 (modified): Take the previous theorem, and suppose that instead of  $\frac{dV}{dt} \leq 0$ , we have that  $\frac{dV}{dt} \leq -\alpha_3(\|x\|)$ , where  $\alpha_3$  is

a class K function then  $D$  is uniformly asymp. stable

Proof: Pick  $r$  such that  $B(0, r) \subset D$ , then pick  $c < \alpha_2^{-1}(\alpha_1(r))$

For any  $\|x(t_0)\| \leq c$ ,  $x(t) \in D \forall t \geq t_0$ , thus the following holds

$$\begin{aligned} \dot{V} &\leq -\alpha_3(\|x\|) \\ &\leq -\alpha_3(\alpha_2^{-1}(V)) \\ &\leq -\alpha(V), \text{ where } \alpha \text{ is a class K function (Lipschitz)} \end{aligned}$$

Let  $y(t)$  satisfy  $\dot{y} = -\alpha(y)$ ,  $y(t_0) = V(x(t_0), t_0)$

$y(t) = \sigma(V(x(t_0)), t - t_0)$  where  $\sigma$  is a class KL function

$$V(t) \leq \sigma(V(x(t_0), t_0), t - t_0) \leq \sigma(\alpha_2(\|x(t_0)\|), t - t_0)$$

Thus:  $\alpha_1(\|x(t)\|) \leq \sigma(\alpha_2(\|x(t_0)\|), t - t_0)$

$$\|x(t)\| \leq \underbrace{\alpha_1^{-1}(\sigma(\alpha_2(\|x(t_0)\|), t - t_0))}_{\text{class KL function}}$$

Addendum: If  $D = \mathbb{R}^n$  and  $\alpha_1, \alpha_2$  are  $K_\infty$  then  $0$  is globally uniformly asymp. stable.

Example: 
$$\begin{aligned} \dot{x}_1 &= -x_1 - g(t)x_2 \\ \dot{x}_2 &= x_1 - x_2 \end{aligned}$$

where  $g(t)$  is continuously differentiable and satisfies  $0 \leq g(t) \leq k$  and  $\dot{g}(t) \leq g(t)$ ,  $\forall t \geq 0$

Pick  $V(x,t) = x_1^2 + (1+g(t))x_2^2$ , thus:

$$\underbrace{x_1^2 + x_2^2}_{\alpha_1(\|x\|)} \leq V(x,t) \leq x_1^2 + (1+k)x_2^2 \leq \underbrace{(1+k)(x_1^2 + x_2^2)}_{\alpha_2(\|x\|)}$$

$K\infty$   $K\infty$

$$\begin{aligned} \frac{dV}{dt} &= x_2^2 \dot{g}(t) + 2x_1(-x_1 - g(t)x_2) + 2(1+g(t))x_2(x_1 - x_2) \\ &= x_2^2 \dot{g}(t) - 2x_1^2 - 2x_1x_2g(t) + 2x_1x_2 - 2x_2^2 + 2x_1x_2g(t) - 2g(t)x_2^2 \end{aligned}$$

$$= -2x_1^2 + 2x_1x_2 - [2 + 2g(t) - \dot{g}(t)]x_2^2$$

but:  $2 + 2g(t) - \dot{g}(t) \geq 2 + g(t) \geq 2$

$$\begin{aligned} \text{Thus } \frac{dV}{dt} &\leq -2x_1^2 + 2x_1x_2 - 2x_2^2 \\ &\leq \underbrace{-(x_1+x_2)^2 - x_1^2 - x_2^2}_{-W_3(x), \text{ continuous, +def}} \end{aligned}$$

Thus 0 is globally uniformly stable.

Example:  $\dot{x} = A(t)x$ ,  $A(t)$  continuous

Define  $V(x,t) = x^T P(t)x$ , where  $P(t)$  is continuously differentiable and

$$\underbrace{c_1 x^T x}_{\alpha_1(\|x\|), K\infty} \leq x^T P(t)x \leq \underbrace{c_2 x^T x}_{\alpha_2(\|x\|), K\infty}, \quad c_1, c_2 > 0$$

$$\frac{dV}{dt} = x^T \dot{P}(t)x + x^T A^T(t)P(t)x + x^T P(t)A(t)x$$

$$= x^T \underbrace{(\dot{P}(t) + A^T(t)P(t) + P(t)A(t))}_{\triangleq Q(t)} x$$

If  $Q(t) \leq -c_3 I$  for some  $c_3 > 0$ , then 0 is globally uniformly asymp. stable